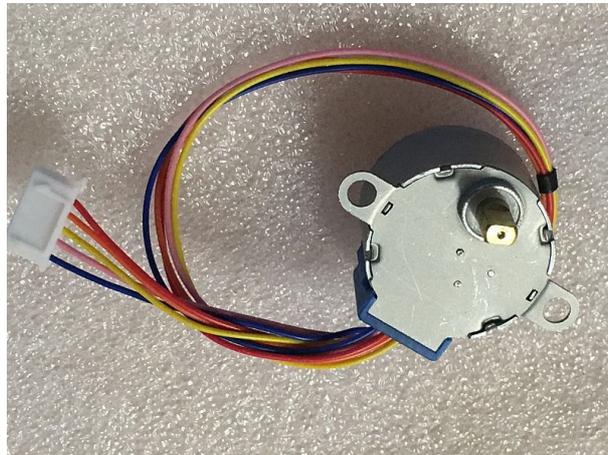


Left Motor

This is the first of 2 motors and is used to drive the left wheel of the robot.

It cannot be fitted until further parts are received (sorry)

This is a type of motor called a stepper motor. Instead of just rotating continuously, electrical pulses are used to make it move in a series of very small steps. This means that it is very easy to control exactly how far it rotates, which means we can determine very accurately how far the robot will move and what angle it will turn – but that is much later in the assembly process