

Right Wheel



Warning: Hold the motor, not the chassis, when pushing the wheel on. You will bend it otherwise

The wheels need to be fitted with the smooth side towards the motor as there isn't much room between the wheels and the sides of the chassis. You will need quite some force to push the wheel on, so be sure to **hold the motor, not the chassis** when pushing it on.

Now you have both wheels on, the robot will move, though not very well as there is nothing at the front yet.

